

# MEAN-FIELD MORAL HAZARD FOR OPTIMAL ENERGY DEMAND RESPONSE MANAGEMENT

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# MOTIVATION & INTUITION

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Electric energy **cannot easily be stored**: supply-demand balance at all times  $\Rightarrow$  Act on the supply side?

**Issue:** Low flexibility (or high cost) production and randomness of renewable energies.

**Solution:** Demand management, facilitated by the development of smart meters.

How can we encourage demand management and reward it optimally?

**In practice.** Tariff offers, price signals...

**Problem.** London Carbon Trial: large variance in the response.

How to improve the responsiveness?

Aïd, Possamaï, and Touzi 2018 - Optimal electricity demand response contracting with responsiveness incentives.

► Principal-Agent problem with moral hazard.

**The Agent** (he) is a risk-averse consumer, who can deviate from his baseline consumption by reducing the mean and the volatility.

$$X_t = x_0 - \int_0^t \alpha_s \cdot \mathbf{1}_d ds + \int_0^t \sigma(\beta_s) \cdot dW_s, \quad t \in [0, T], \quad (1)$$

where  $W$  is a  $d$ -dimensional Brownian Motion.

A control process for the Agent is a pair  $\nu := (\alpha, \beta) \in \mathcal{U}$ :

- $\alpha$  is the effort to reduce his consumption **in mean**;
- $\beta$  is the effort to reduce **the variability** of his consumption.

**The Principal** (she) is a producer (or a retailer) subject to energy generation costs and to consumption volatility costs.

## STARTING FROM ONE CONSUMER...

The Principal wants to incentivise the consumer to reduce the mean and the volatility of his consumption.

**Moral Hazard:** She observes the deviation consumption  $X$  of the Agent in continuous time, but not the effort  $\nu$  he makes.

► She offers him a contract indexed on his deviation consumption:

$$\xi_T = \xi_0 - \int_0^T \mathcal{H}(X_s, \zeta_s) ds + \int_0^T Z_s dX_s + \frac{1}{2} \int_0^T \Gamma_s d\langle X \rangle_s + \frac{1}{2} R_A \int_0^T Z_s^2 d\langle X \rangle_s,$$

for an optimal choice of  $\zeta = (Z, \Gamma)$ .

### Results.

- Optimal contracting allows the system to bear more risk as the resulting volatility may increase;
- The control of the consumption volatility can lead to a significant increase of responsiveness.

## ... AND EXTEND IT TO A MEAN FIELD OF AGENTS

The producer is facing a Mean-Field (MF) of correlated consumers and optimise in mean.

Find a way for the Principal to benefit from dealing with this MF of consumers.

She knows the law of the consumption of the pool of consumers.

► She can design a new contract in order to **penalise** / **reward** a consumer who makes **less** / **more** effort than the rest of the pool.

**Intuition.**

Optimal contracts should consists of two parts:

- A classical part indexed on the deviation consumption of the Agent (previous contract, as in Aïd, Possamaï, and Touzi 2018);
- An additional part indexed on the law of the deviation consumption of others.

**Drift and volatility control.**

**Cvitanović, Possamaï, and Touzi 2018** - Dynamic Programming Approach to Principal-Agent Problems.

**Contracting with many Agents.**

**Élie and Possamaï 2016** - Contracting theory with competitive interacting Agents.

**Élie, Mastrolia, and Possamaï 2018** - A tale of a Principal and many many Agents.

**Mean-Field Games and Common Noise.**

**Carmona and Delarue 2018** - Probabilistic theory of mean field games with applications II.

**Carmona, Delarue, and Lacker 2016** - Mean Field Games with common noise.



# A PRINCIPAL - MF AGENTS PROBLEM

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# THE REPRESENTATIVE AGENT

Classical MFG framework: All agents are identical.

► Focus on a **typical small consumer** who has no impact on the global consumption: **the representative Agent**.

His deviation from his baseline consumption is given by:

$$X_t = x_0 - \int_0^t \alpha_s \mathbf{1}_d ds + \int_0^t \sigma(\beta_s) \cdot dW_s + \int_0^t \sigma^\circ dW_s^\circ, \quad t \in [0, T]. \quad (2)$$

where

- $W$  is a  $d$ -dimensional idiosyncratic noise;
- $W^\circ$  is a one-dimensional **common noise** (common random environment as climate hazards).

A control process for the Agent is still a pair  $\nu := (\alpha, \beta) \in \mathcal{U}$ :

- $\alpha$  is the effort to reduce his consumption **in mean**;
- $\beta$  is the effort to reduce **the variability** of his consumption.

In Aïd, Possamaï, and Touzi 2018, the Principal offers a contract to an Agent indexed on his deviation consumption  $X$ .

In the MF case, the Principal faces a Mean Field of Agents and can therefore benefit from this.

She can compute the conditional law of the deviation consumption of other consumers w.r.t the common noise, denoted by  $\hat{\mu}$ .

⇒ New form of contracts:  $\xi(X, \hat{\mu})$ .

Optimisation problem of the representative consumer:

$$V_0^A(\xi, \hat{\mu}) := \sup_{\mathbb{P} \in \mathcal{P}} \mathbb{E}^{\mathbb{P}} \left[ U_A \left( \xi(X, \hat{\mu}) - \int_0^T (c(\nu_t^{\mathbb{P}}) - f(X_t)) dt \right) \right], \quad (3)$$

where  $c$  is a cost function,  $f$  denotes the preference of the Agent toward his deviation consumption, and  $U_A(x) = -e^{-R_A x}$ .

Applying the chain rule with common noise in Carmona and Delarue 2018 to the dynamic value function of the Agent, we obtain the following form for the contract:

$$\begin{aligned}\xi_T = & \xi_0 - \int_0^T \mathcal{H}(X_s, \zeta_s, \hat{\alpha}_s^*, \hat{\mu}_s) ds + \int_0^T Z_s dX_s + \frac{1}{2} \int_0^T (\Gamma_s + R_A Z_s^2) d\langle X \rangle_s \\ & + \int_0^T \mathbb{E}^{\hat{\mu}_s} \left[ Z_s^\mu(\hat{X}_s) d\hat{X}_s \right] + \frac{1}{2} R_A \int_0^T \mathbb{E}^{\hat{\mu}_s} \mathbb{E}^{\hat{\mu}_s} \left[ Z_s^\mu(\hat{X}_s) Z_s^\mu(\check{X}_s) d\langle \hat{X}, \check{X} \rangle_s \right] \\ & + R_A \int_0^T Z_s \mathbb{E}^{\hat{\mu}_s} \left[ Z_s^\mu(\hat{X}_s) d\langle X, \hat{X} \rangle_s \right],\end{aligned}$$

where

- $\zeta_t = (Z_t, Z_t^\mu, \Gamma_t)$  is a triple of parameters chosen by the Principal;
- $\hat{\alpha}^*$  is the optimal drift effort of other consumers;
- $\hat{X}$  the deviation consumption of others,  $\check{X}$  a copy;
- $\mathbb{E}^{\hat{\mu}}$  expectation under  $\hat{\mu}$  (w.r.t the common noise).

## What is hidden behind this contract ?

The contract is in fact indexed on:

- $X$ , the deviation consumption of the representative consumer;
- $W^\circ$ , the common noise.

$$\begin{aligned} \xi_T = \xi_0 & - \int_0^T \mathcal{H}(X_s, \zeta_s) ds + \int_0^T Z_s dX_s + \frac{1}{2} \int_0^T (\Gamma_s + R_A Z_s^2) d\langle X \rangle_s \\ & + \int_0^T \sigma^\circ \bar{Z}_s^\mu dW_s^\circ + \frac{1}{2} R_A \int_0^T (\bar{Z}_s^\mu)^2 (\sigma^\circ)^2 ds + R_A \int_0^T Z_s \bar{Z}_s^\mu (\sigma^\circ)^2 ds, \end{aligned}$$

where  $\bar{Z}_t^\mu := \hat{\mathbb{E}}^{\hat{\mu}}[Z_t^\mu(\hat{X}_t)]$ .

- If the Principal can offer contract depending directly on the common noise, she can offer this contract, indexed by  $\bar{\zeta}_t = (Z_t, \bar{Z}_t^\mu, \Gamma_t)$ .
- Contracting on  $\hat{\mu}$  or  $W^\circ$  leads in fact to the same form of contract.

Given a contract of the previous form,

- ▶ optimal effort  $\nu$  of the representative Agent:

$$\nu^* = (\alpha^*(Z), \beta^*(\Gamma)) \Rightarrow dX_t = \alpha^*(Z) \cdot 1_d dt + \sigma^*(\Gamma) \cdot dW_t + \sigma^\circ dW_t^\circ,$$

same as in Aïd, Possamaï, and Touzi 2018 and does not depend neither on  $Z^\mu$  nor on  $\hat{\mu}$ ;

- ▶ MF equilibrium: optimal efforts are the same for all consumers,  $\hat{X} \stackrel{\mathcal{L}}{\sim} X$  and  $\hat{\mu} = \mu^X$ ;
- ▶ from the Principal's point of view, the contract  $\xi$  is a function of  $X$  and  $\mu^X$ , the conditional law of  $X \Rightarrow$  McKean Vlasov problem.

## PRINCIPAL'S PROBLEM

The Principal wants to minimise, the sum of the conditional expectation of:

- ▶ the compensation  $\xi$  paid to the consumers;
- ▶ the production cost of the consumption deviation,  $\int_0^T g(X_t)dt$ ;
- ▶ the quadratic variation of the deviation consumption,  $\int_0^T d\langle X \rangle_t$ ;

with respect to the common noise.

Her problem is reduced to a standard control problem:

$$V^P := \sup_{\zeta \in \mathcal{V}} \mathbb{E} \left[ U^P \left( -\mathbb{E}^{\mu^L} [L_T] \right) \right], \quad L_T = \xi_T + \int_0^T g(X_s)ds + \frac{h}{2} \int_0^T d\langle X \rangle_s,$$

where  $\mu^L$  is the conditional law of  $L$  and  $U^P(c) = -e^{-R_P c}$  or  $U^P(c) = c$ .

Two state variables: the **conditional** law of  $X$  ( $\mu^X$ ) and the **conditional** law of  $L$  ( $\mu^L$ )  $\Rightarrow$  HJB technics.

Optimal indexation on the law

$$Z^{\mu,*} = -Z^* + \frac{R_P}{R_A + R_P} \bar{u}_{\mu^x}^P,$$

leads to the optimal contract:

$$\begin{aligned} \xi_t = \xi_0 & - \underbrace{\int_0^t \mathcal{H}(X_s, \mu_s^x, \zeta_s^*, \alpha_s^*) ds}_{\text{Hamiltonian}} + \underbrace{\int_0^t Z_s^* (dX_s - \tilde{\mathbb{E}}^{\mu_s} [d\tilde{X}_s])}_{\text{Penalisation w.r.t the others}} \\ & + \underbrace{\frac{1}{2} \int_0^t \Gamma_s^* d\langle X \rangle_s}_{\text{Compensation for volatility control}} + \underbrace{\frac{R_P}{R_A + R_P} \int_0^t \bar{u}_{\mu^x}^P \tilde{\mathbb{E}}^{\mu_s^x} [d\tilde{X}_s]}_{\text{Payment on others}} \\ & + \underbrace{\frac{1}{2} R_A \int_0^t \left( (Z_s^*)^2 (d\langle X \rangle_s - (\sigma^\circ)^2 ds) + \frac{R_P^2}{(R_A + R_P)^2} (\sigma^\circ)^2 (\bar{u}_{\mu^x}^P)^2 ds \right)}_{\text{Compensation for risk due to the risk aversion of the consumer } (R_A)}. \end{aligned}$$



Let  $X^\circ$  be the deviation consumption **without common noise**:

$$dX_t^\circ = -\alpha^*(Z_t^*)dt + \sigma^*(\Gamma_t^*) \cdot dW_t,$$

we can write the contract in term of  $X^\circ$  and  $W^\circ$ :

$$\begin{aligned} \xi_T = \xi_0 &- \int_0^T \mathcal{H}(X_s, \zeta_s^*) ds + \int_0^T Z_s^* dX_s^\circ + \frac{1}{2} \int_0^T (\Gamma_s^* + R_A (Z_s^*)^2) d\langle X^\circ \rangle_s \\ &+ \frac{R_P}{R_A + R_P} \sigma^\circ \int_0^T \bar{u}_{\mu^x}^P dW_s^\circ + \frac{1}{2} \frac{R_A R_P^2}{(R_A + R_P)^2} (\sigma^\circ)^2 \int_0^T (\bar{u}_{\mu^x}^P)^2 ds. \end{aligned}$$

Risk-neutral case ( $R_P = 0$ )  $\Rightarrow$  Classical contract for drift and volatility control, **indexed on  $X^\circ$** , that is the part of the deviation consumption which is **really controlled** by the Agent.

# LINEAR ENERGY VALUE DISCREPANCY

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## COMPARISON WITH CLASSICAL CONTRACTS

If the energy value discrepancy is linear, i.e.  $(f - g)(x) = \delta x$ ,  $x \in \mathbb{R}$ :

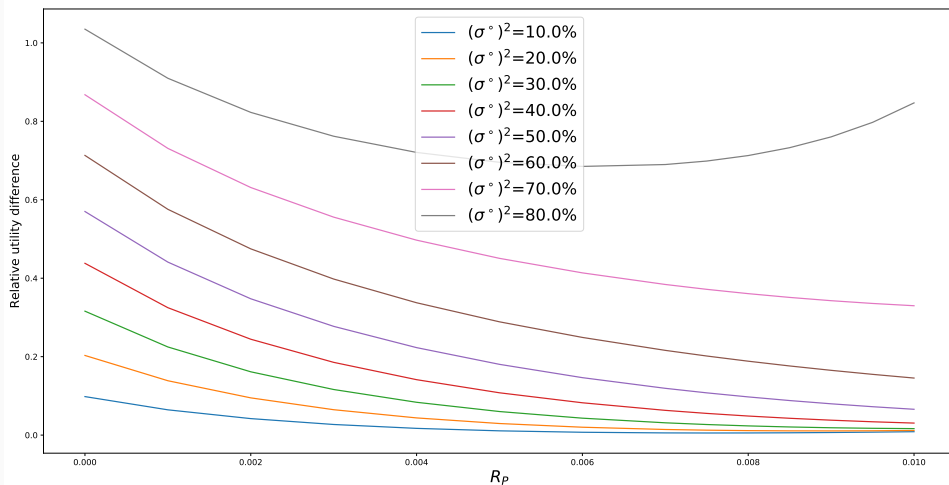
- ▶ the optimal payment rates are deterministic functions of time;
- ▶ the optimal  $Z^*$  and  $\Gamma^*$  are the same whether the Principal is risk-averse or risk-neutral;
- ▶ the payment  $Z^{\mu,*}$  allows the Principal to choose the risk she wants to bear:

$$Z_t^{\mu,*} = -Z_t^* + \frac{R_P}{R_A + R_P} \delta(T - t).$$

We can compare the efforts and the utility of the Principal when she offers contracts indexed by  $\zeta^0 = (Z, 0, \Gamma)$ :

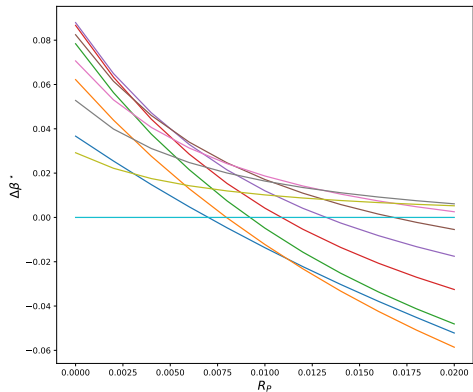
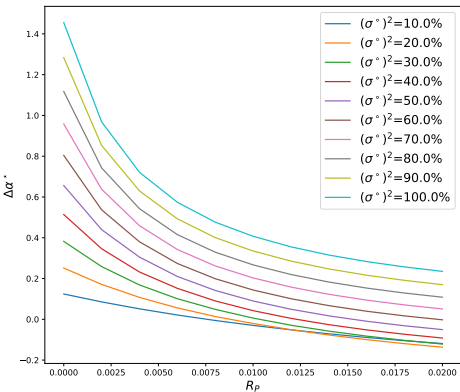
$$\xi_T = \xi_0 - \int_0^T \mathcal{H}(X_s, \zeta_s^0) ds + \int_0^T Z_s dX_s + \frac{1}{2} \int_0^T (\Gamma_s + R_A Z_s^2) d\langle X \rangle_s,$$

# GAIN IN UTILITY FOR THE PRINCIPAL



**Figure:** Relative utility difference.  
Variation with respect to  $R_P$  and  $\sigma^o$ .

# EFFORT OF THE AGENTS



**Figure:** Relative gain on efforts.  
Variation with respect to  $R_p$  and  $\sigma^\circ$ .

# CONCLUSION

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Principal – Mean–Field Agents model, with drift and volatility control, under moral hazard.

- ▶ New form of contracts allowing the Principal to benefit from facing a MF of Agents.
- ▶ This type of contracts allows her to choose the remaining risk she wants to bear.

At least in the linear energy value discrepancy case,

- ▶ there is a gain in utility for the Principal;
- ▶ the optimal efforts of the consumers are the same whether the Principal is risk-averse or risk-neutral;
- ▶ the consumers make more effort if the risk-aversion parameter of the Principal is small.

THANK YOU FOR YOUR ATTENTION